

AutoML:

From Full Automation to A Human-Centric Approach

Prof. Marius Lindauer



Feb'2011

Ich

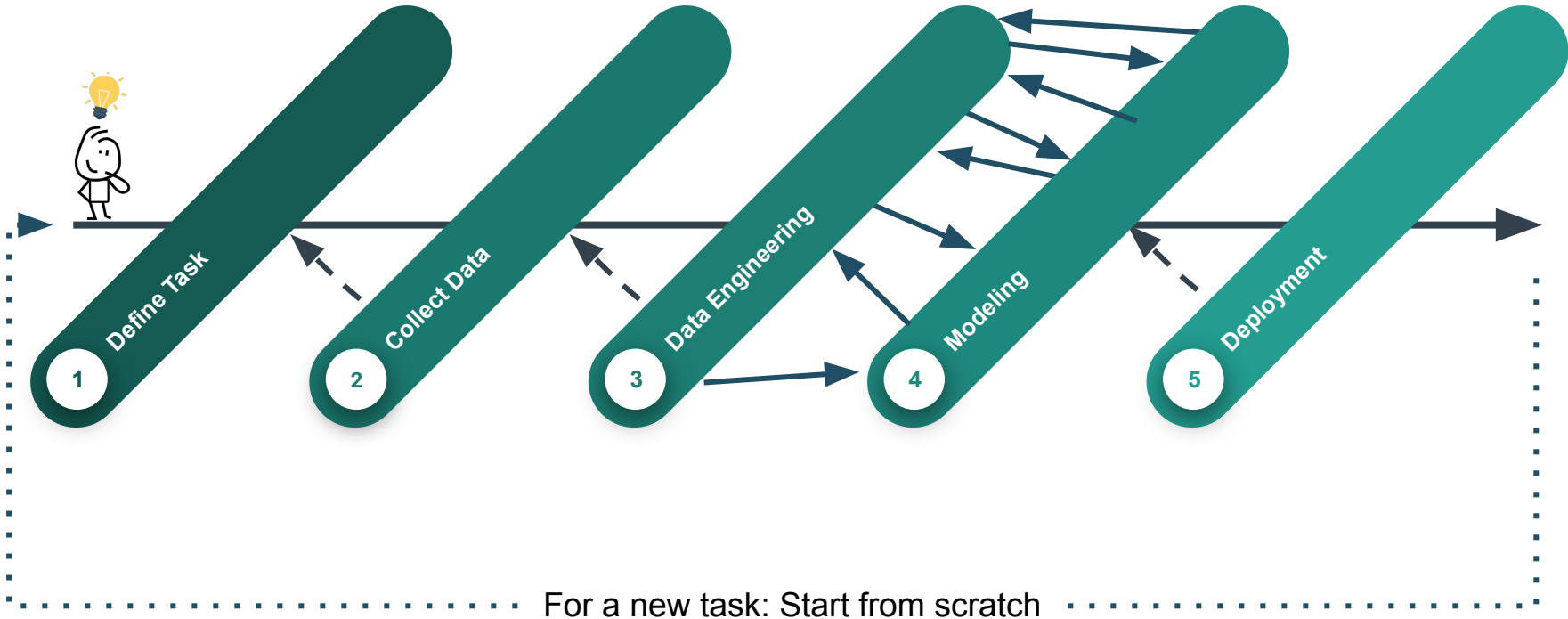
Frank
Hutter

Holger

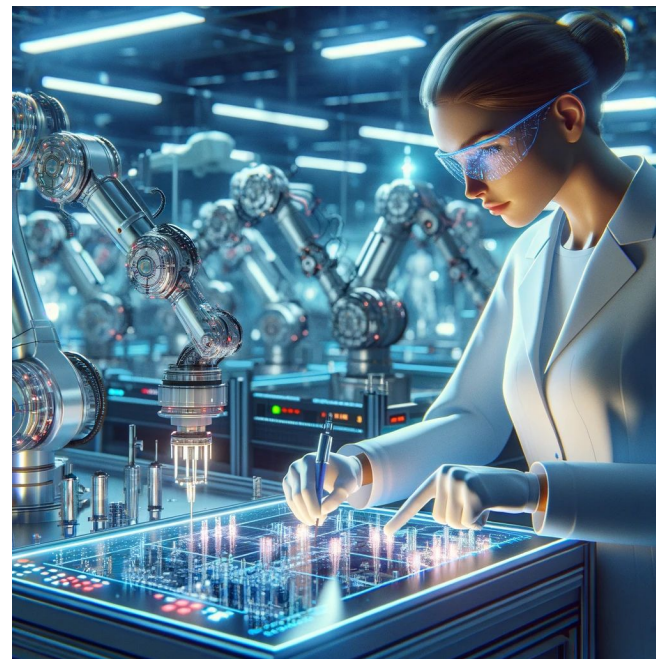
Kevin
Leyton-Brown



Why does ML development take a lot of time?



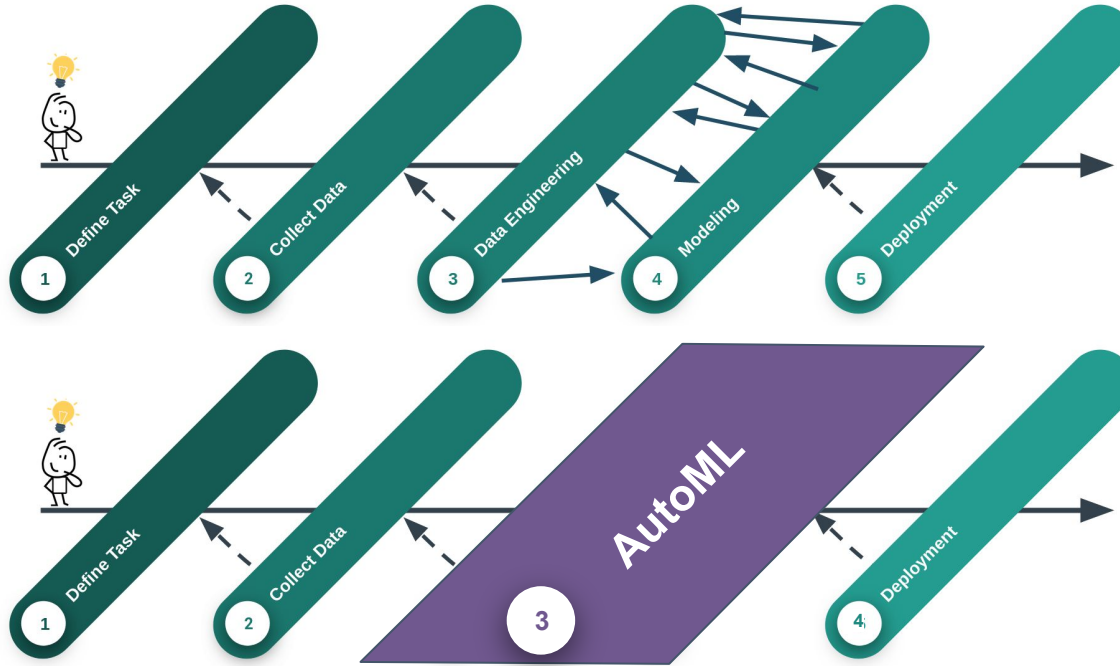
From ML Alchemy to Science

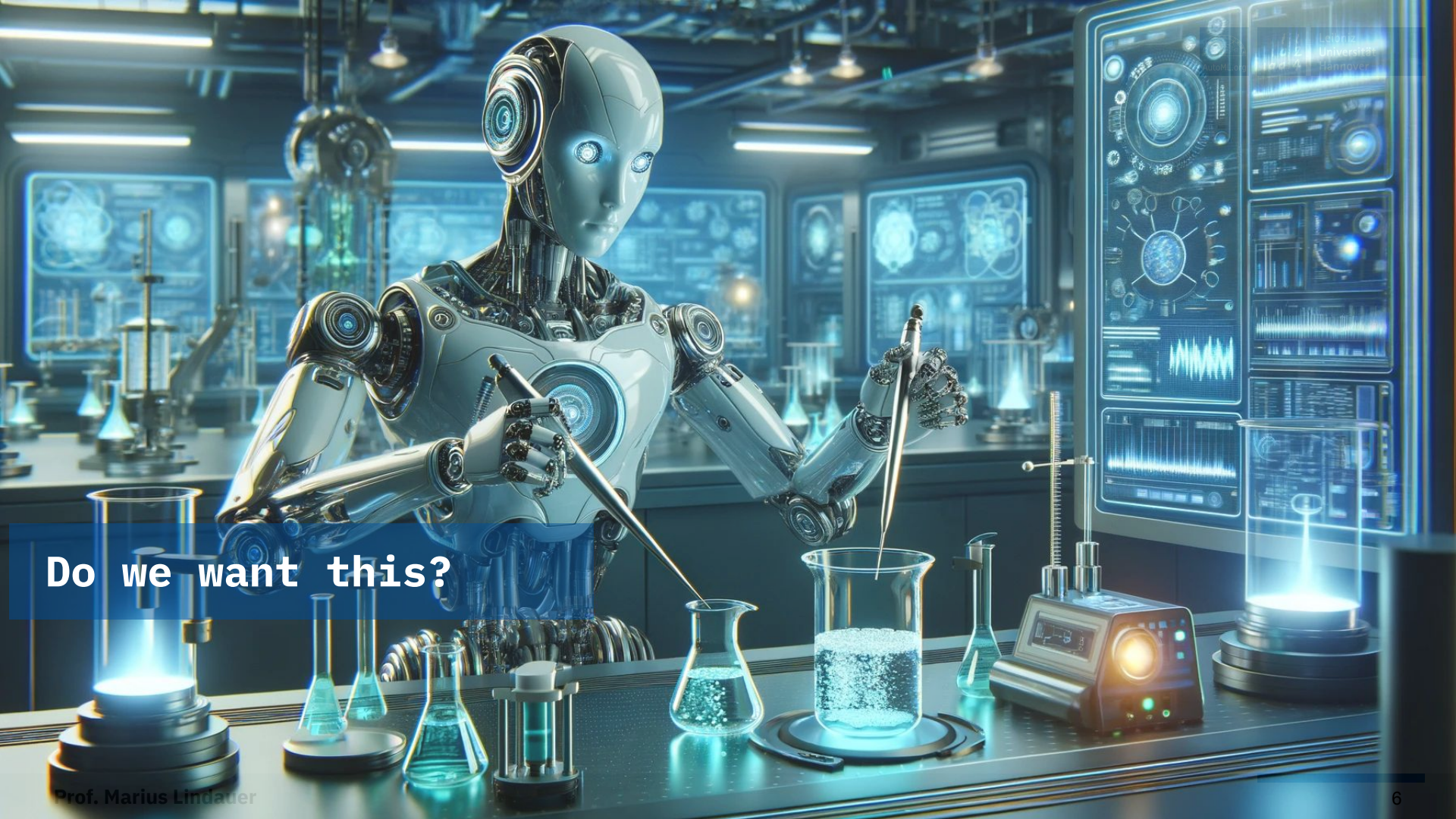


“You can teach an old dog new tricks” [[Ruffinelli et al. 2020](#)]

→ Hyperparameter optimization might not be the only required solution, but without it, it will also be hard.

ML vs AutoML





Do we want this?



This might be better!

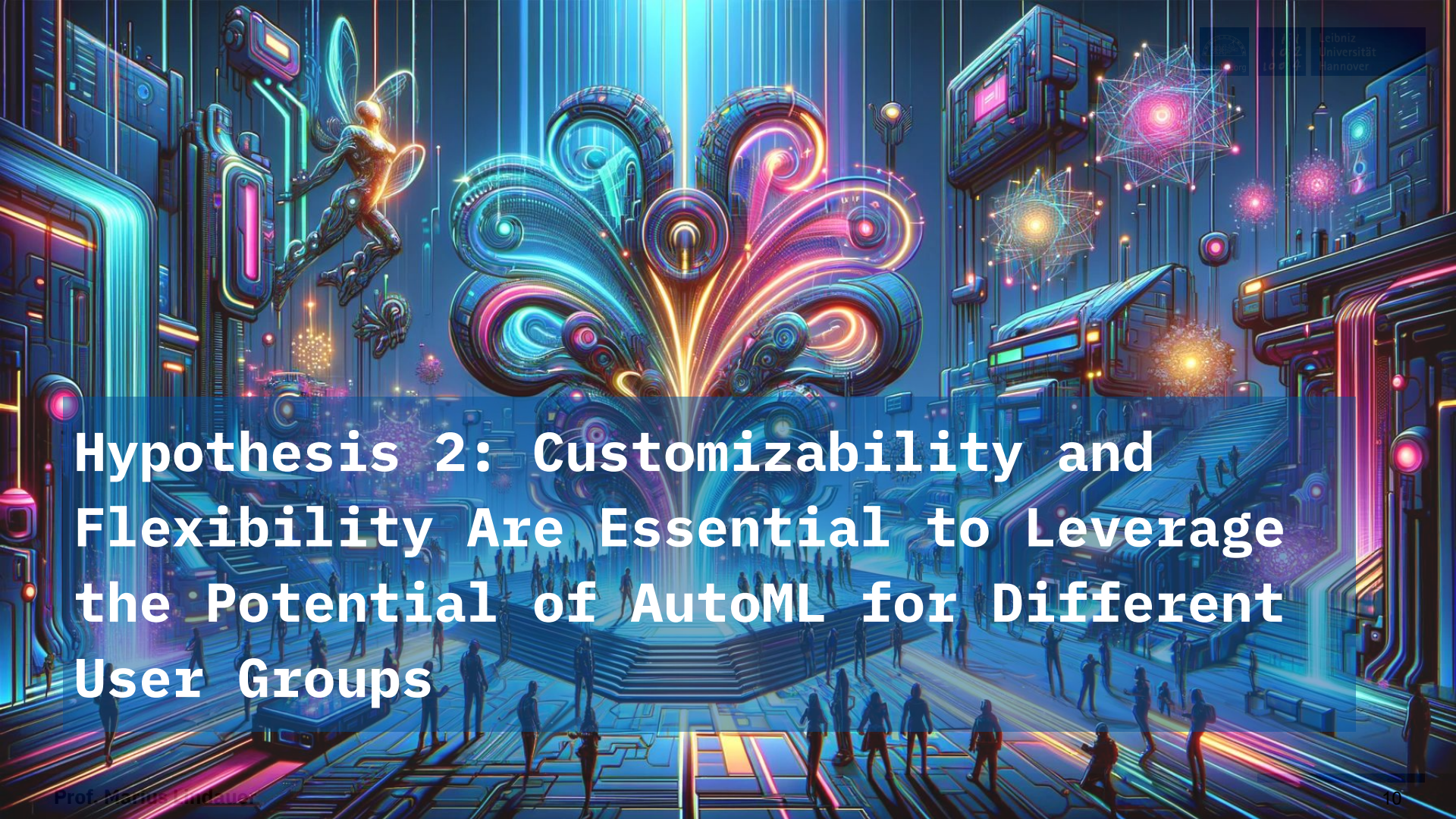
5 Hypotheses for Human-Centered AutoML



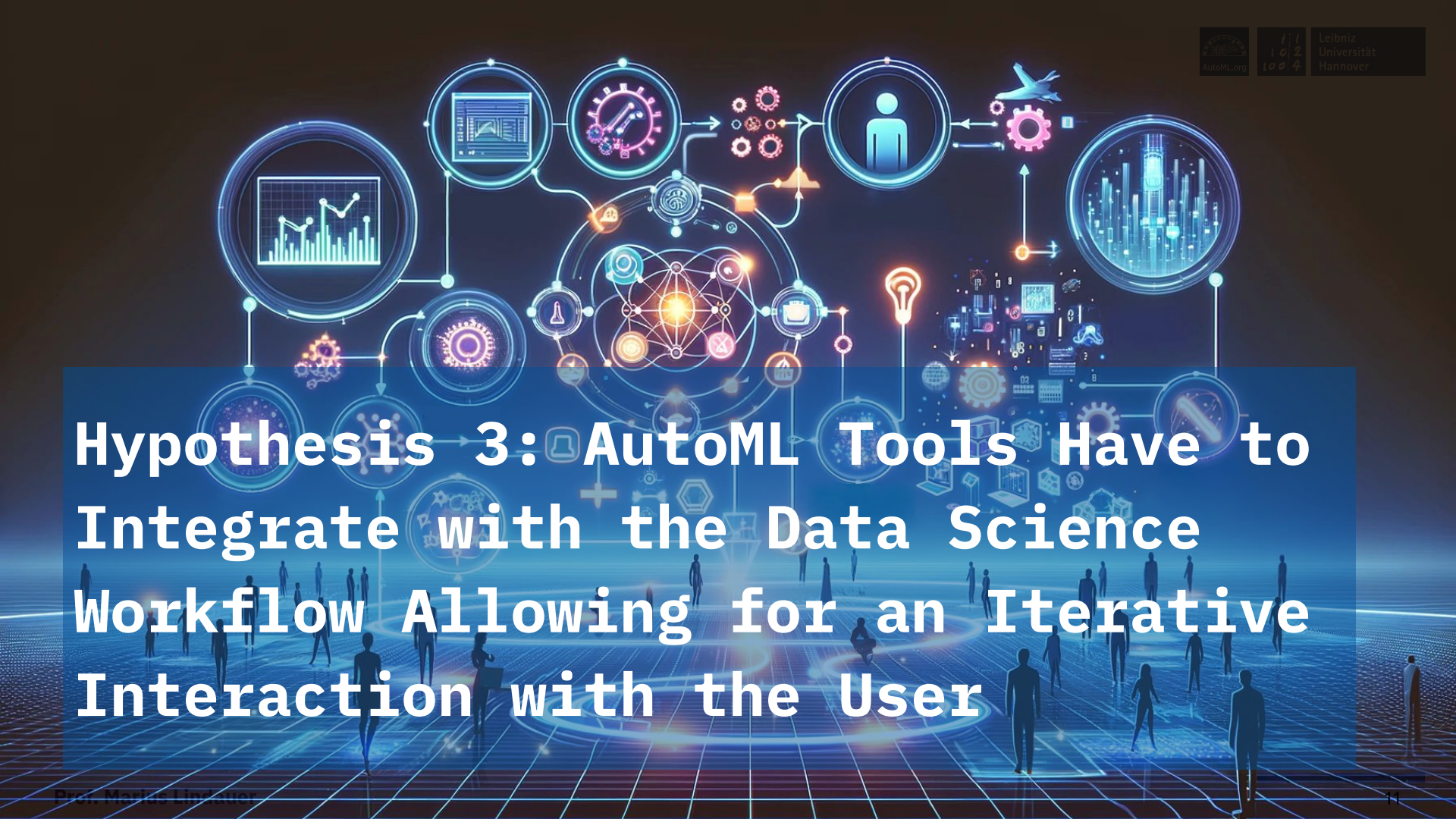
[Lindauer, Karl, Klier, Moosbauer, Tornede, Müller, Hutter, Feuerer, Bischl. Submission to ICML'24]



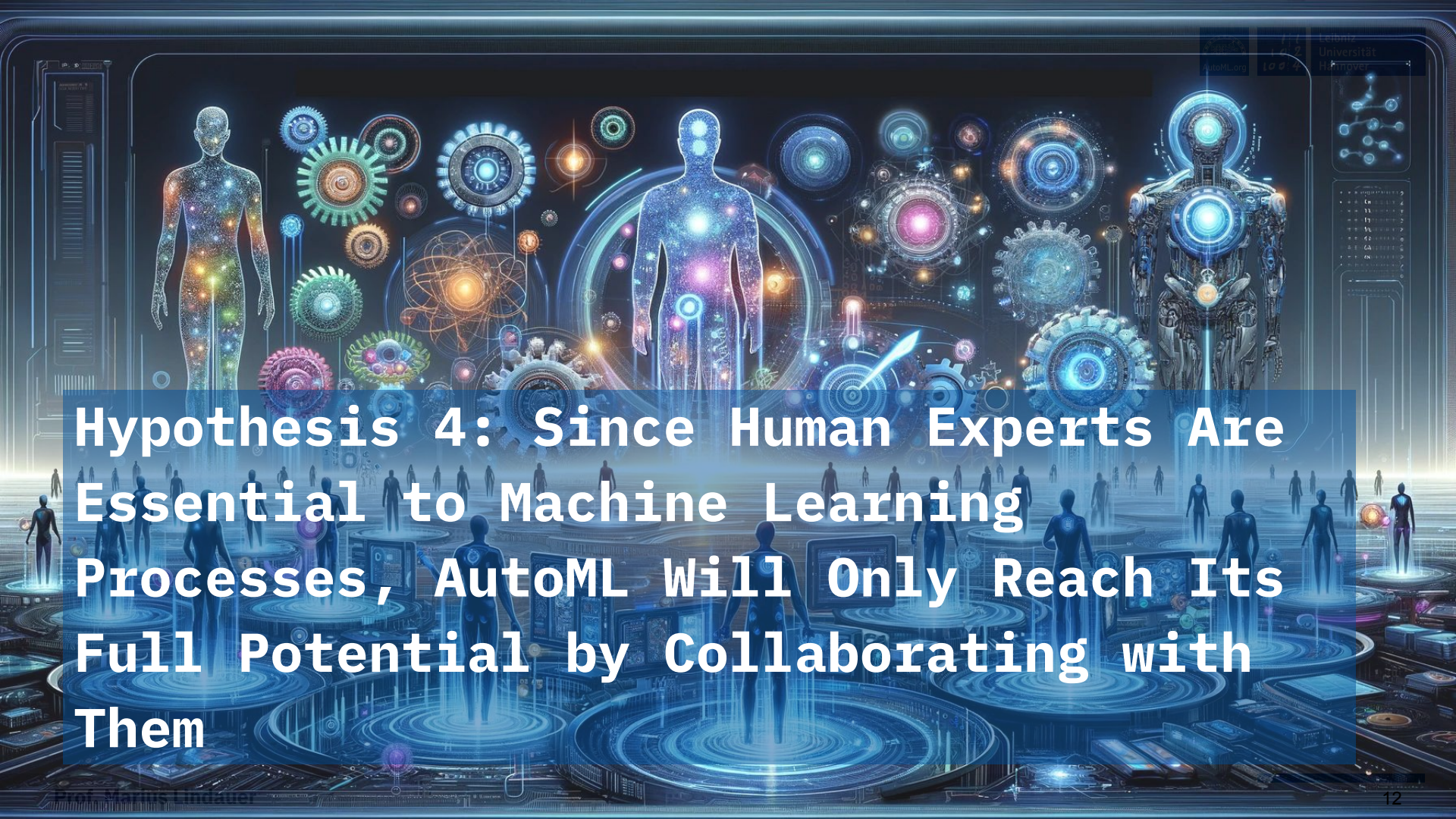
Hypothesis 1: Transparency and Interpretability are Key for ML and AutoML in Many Applications and on Many Levels



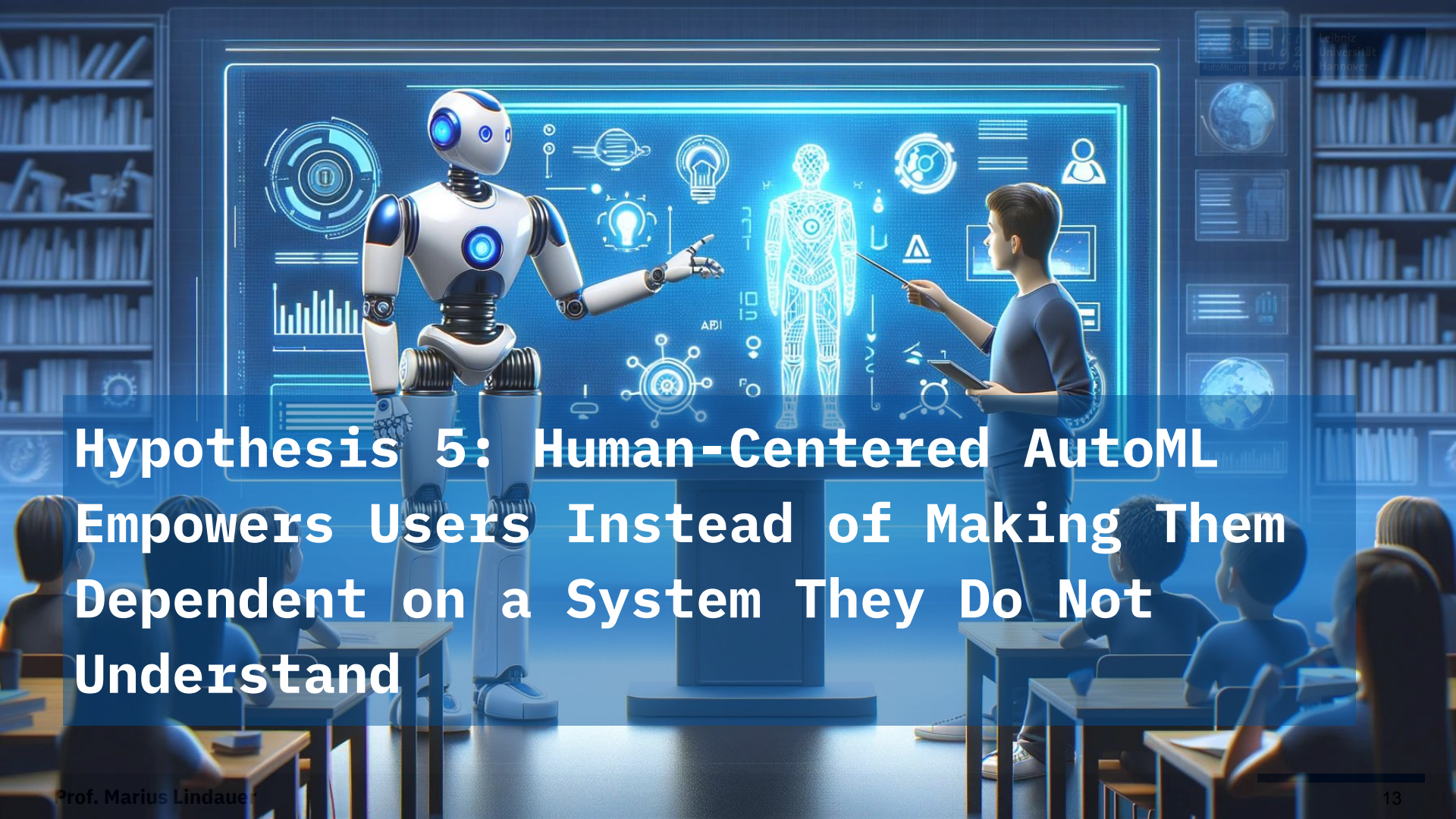
Hypothesis 2: Customizability and Flexibility Are Essential to Leverage the Potential of AutoML for Different User Groups



Hypothesis 3: AutoML Tools Have to Integrate with the Data Science Workflow Allowing for an Iterative Interaction with the User

The background is a complex digital environment. It features several glowing human silhouettes, some appearing as data points or nodes. There are numerous gears of various sizes and colors (blue, green, orange, purple) scattered throughout. The scene is filled with light trails, circular patterns, and abstract data visualizations. In the top right corner, there's a small interface element with the text 'Universität' and 'Hilfen'.

Hypothesis 4: Since Human Experts Are Essential to Machine Learning Processes, AutoML Will Only Reach Its Full Potential by Collaborating with Them



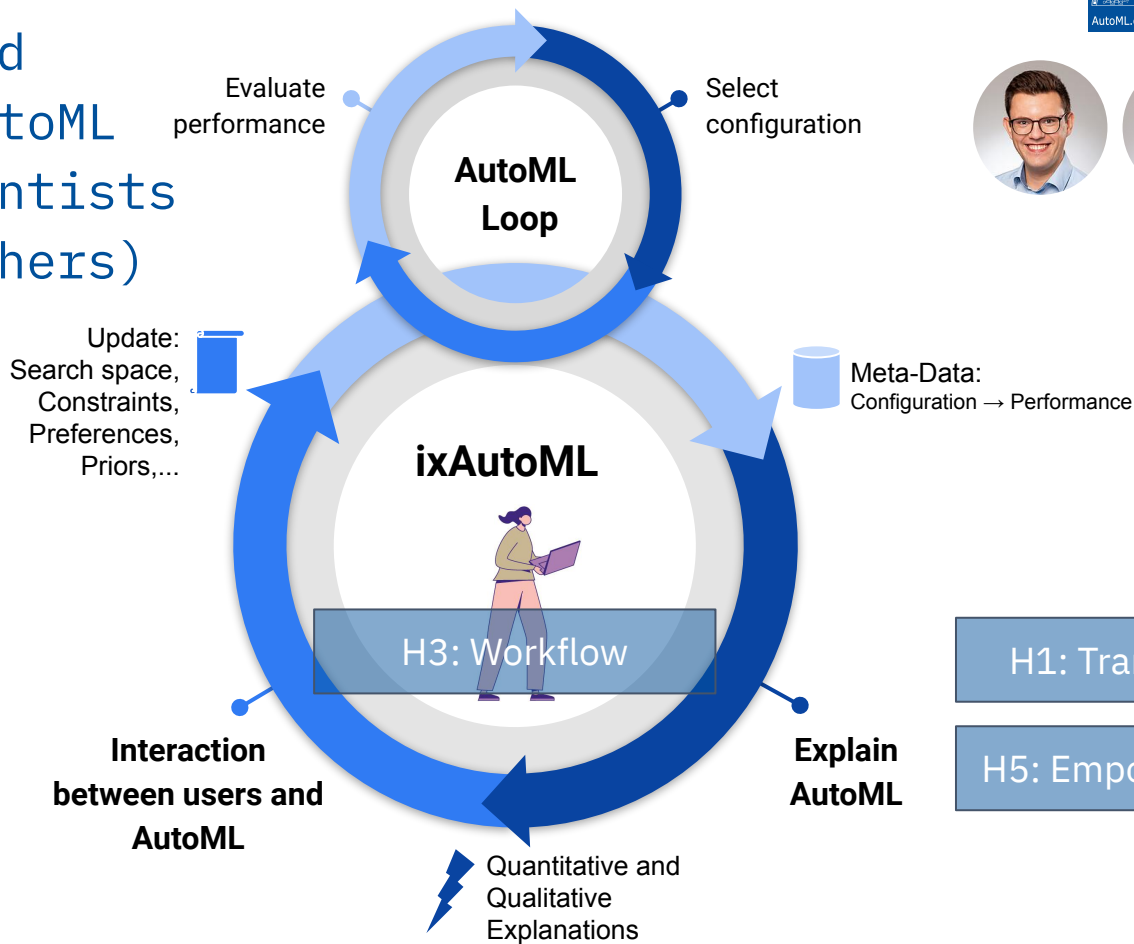
Hypothesis 5: Human-Centered AutoML Empowers Users Instead of Making Them Dependent on a System They Do Not Understand

ixAutoML:

interactive and explainable AutoML
(for Data Scientists and ML researchers)

H2: Customizability

H4: Collaboration



Explaining I: Partial Dependence Plots

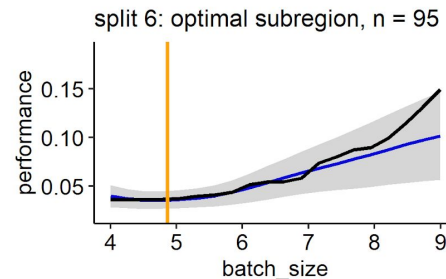
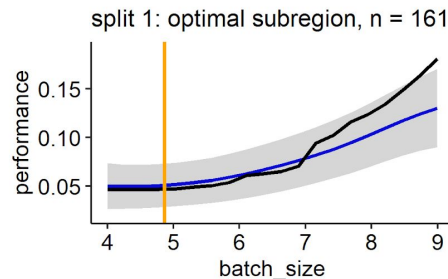
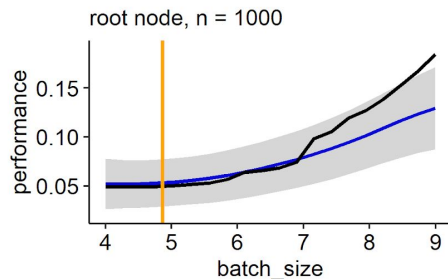
Explaining Hyperparameter Effects via PDPs

[[Moosbauer et al. NeurIPS'22](#)]

Ground truth

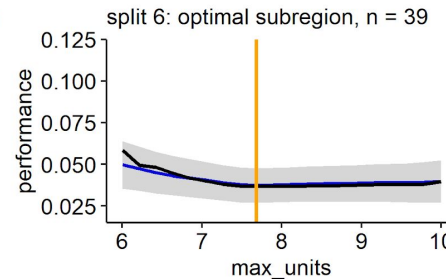
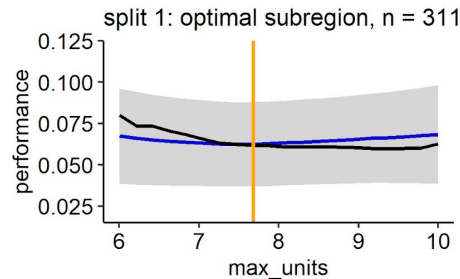
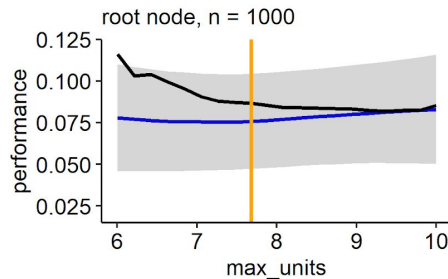
PDP

incumbent



Subregion definition:
`weight_decay <= 0.086`

Subregion definition:
`num_layers <= 4.5,`
`weight_decay <= 0.0178,`
`max_dropout <= 0.6966`



Subregion definition:
`batch_size <= 7.5329`

Subregion definition:
`max_dropout <= 0.7305,`
`num_layers <= 4.5,`
`batch_size <= 6.1739,`
`weight_decay <= 0.0172`

Partial Dependence Plots

[[Moosbauer et al. NeurIPS'22](#)]

For, a subset S of the hyperparameters, the partial dependence function is:

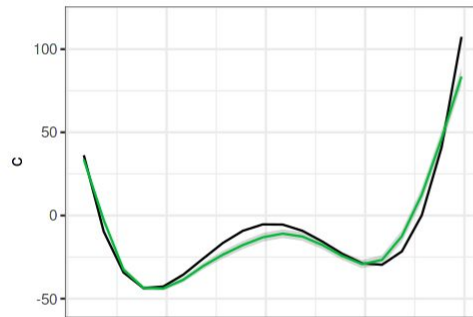
$$c_S(\lambda_S) := \mathbb{E}_{\lambda_C} [c(\lambda)] = \int_{\Lambda_C} c(\lambda_S, \lambda_C) d\mathbb{P}(\lambda_C)$$

and can be approximated by Monte-Carlo integration on a surrogate model:

$$\hat{c}_S(\lambda_S) = \frac{1}{n} \sum_{i=1}^n \hat{m}(\lambda_S, \lambda_C^{(i)})$$

where $\left(\lambda_C^{(i)}\right)_{i=1, \dots, n} \sim \mathbb{P}(\lambda_C)$ and λ_S for a set of grid points.

→ Average of ICE curves.



Green: PDP
Black: Ground truth

Partial Dependence Plots with Uncertainties

[Moosbauer et al. NeurIPS'22]

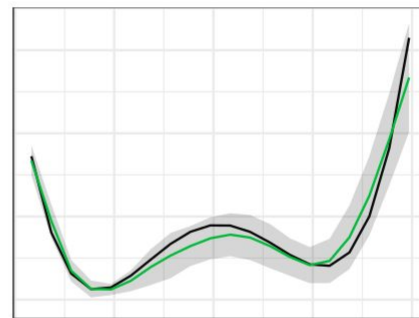
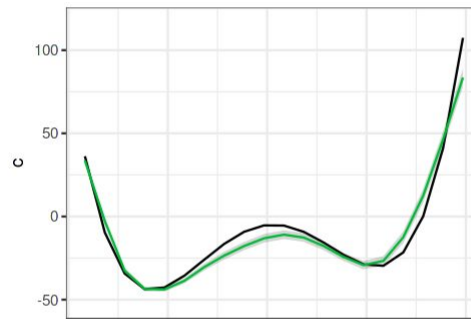
$$\begin{aligned} & \hat{s}_S^2(\lambda_S) \\ &= \mathbb{V}_{\hat{c}}[\hat{c}_S(\lambda_S)] \\ &= \mathbb{V}_{\hat{c}}\left[\frac{1}{n}\sum_{i=1}^n \hat{c}\left(\lambda_S, \lambda_C^{(i)}\right)\right] \\ &= \frac{1}{n^2} \mathbf{1}^\top \hat{K}(\lambda_S) \mathbf{1}. \end{aligned}$$

→ requires a kernel correctly specifying the covariance structure (e.g., GPs).

Approximation:

$$\hat{s}_S^2(\lambda_S) \approx \frac{1}{n} \sum_{i=1}^n \hat{K}(\lambda_S)_{i,i}$$

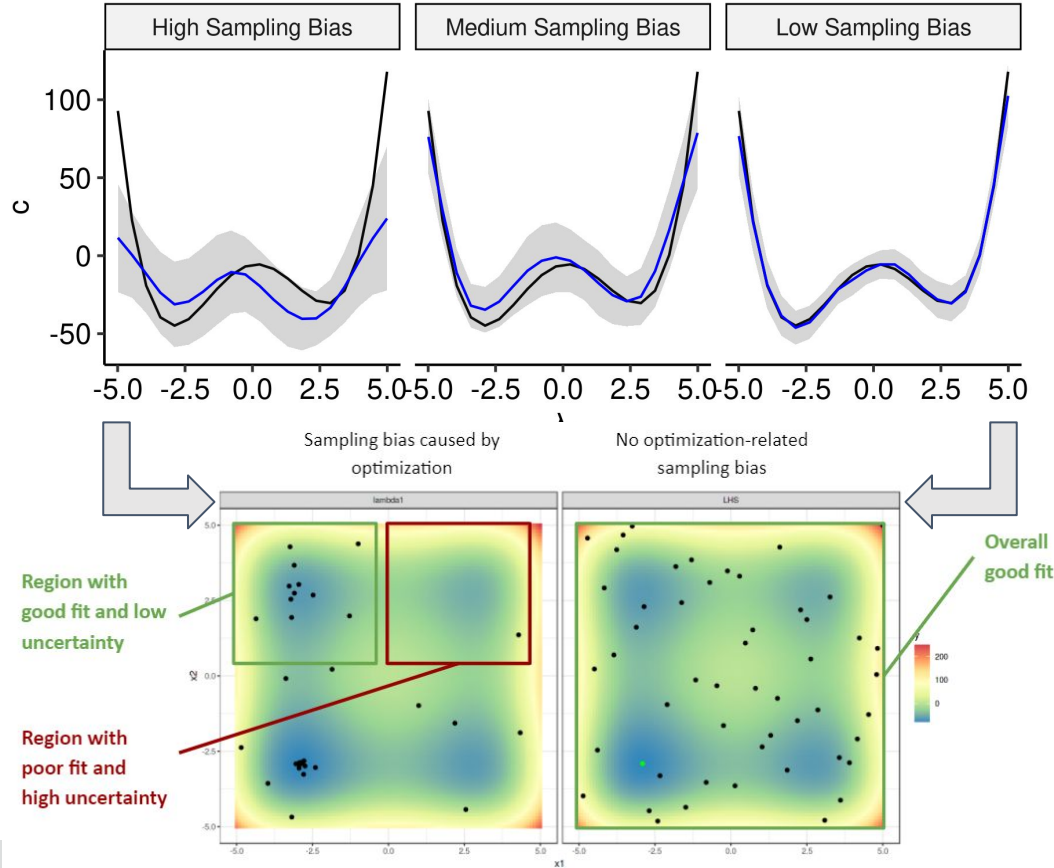
→ Model-agnostic (local) approximation



Ground truth
PDP
Uncertainty

Impact of Sampling Bias in Explaining AutoML

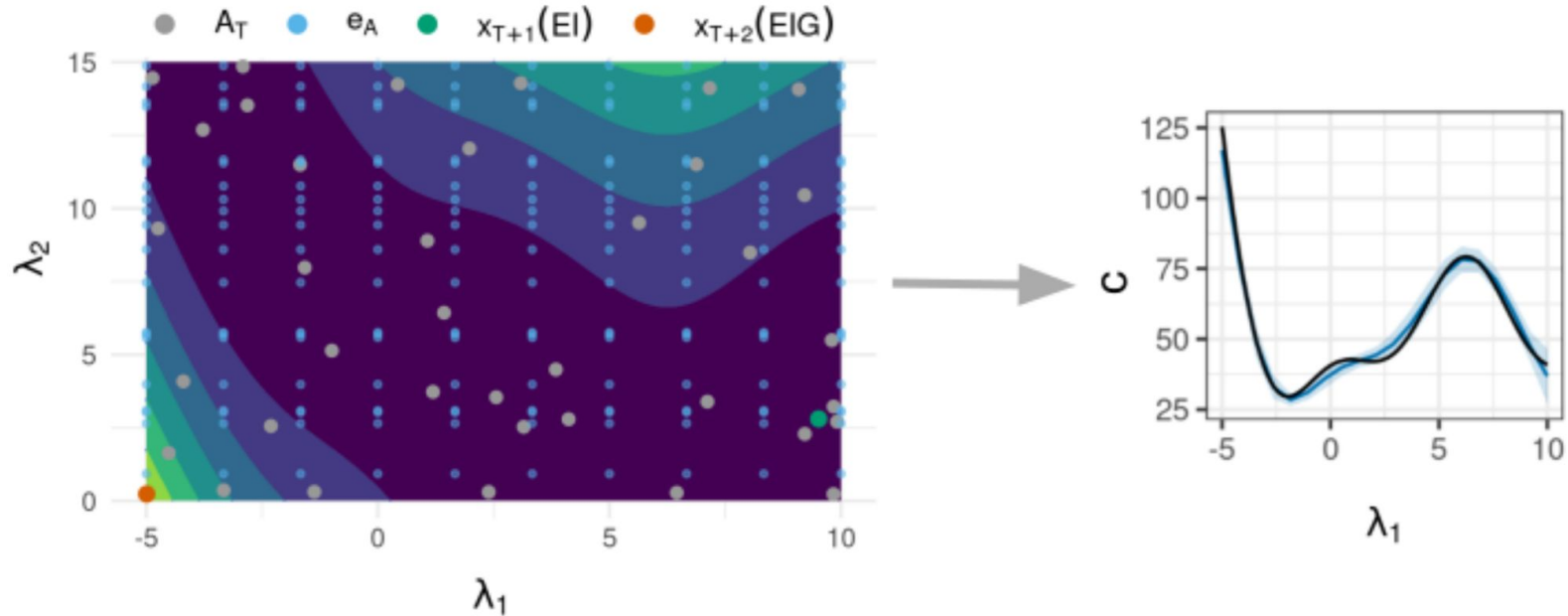
[Moosbauer et al. NeurIPS'22]



Exploration Strategy for Interpretability

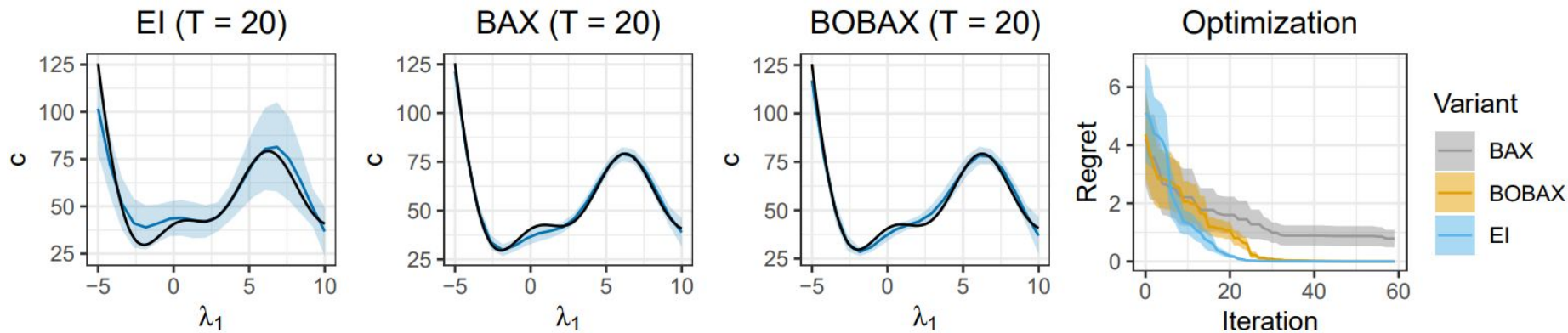
[Moosbauer et al. 2023]

- Main idea: Optimize for getting better interpretability of the HPO problem



Exploration Strategy for Interpretability

[[Moosbauer et al. 2023](#)]



1. Bayesian Optimization (BO) with EI leads to bad PDPs
2. Bayesian Algorithm Execution (BAX) leads to good PDPs, but poor optimization performance
3. Interleaving BO and BAX leads to good PDPs and strong optimization performance

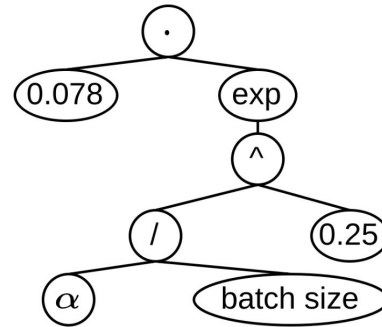
Explaining II: Symbolic Regression



- Hyperparameter optimization (HPO) methods can find well-performing configurations efficiently
- Their **lack of transparency** can lead to missing trust of the users
[[Hasebrock et al. 2023](#)]

Symbolic Explanations to the Rescue!

$$\begin{aligned} s(\alpha, \text{batch size}) \\ = 0.078 \cdot \exp\left(\left(\alpha / \text{batch size}\right)^{\frac{1}{4}}\right) \end{aligned}$$

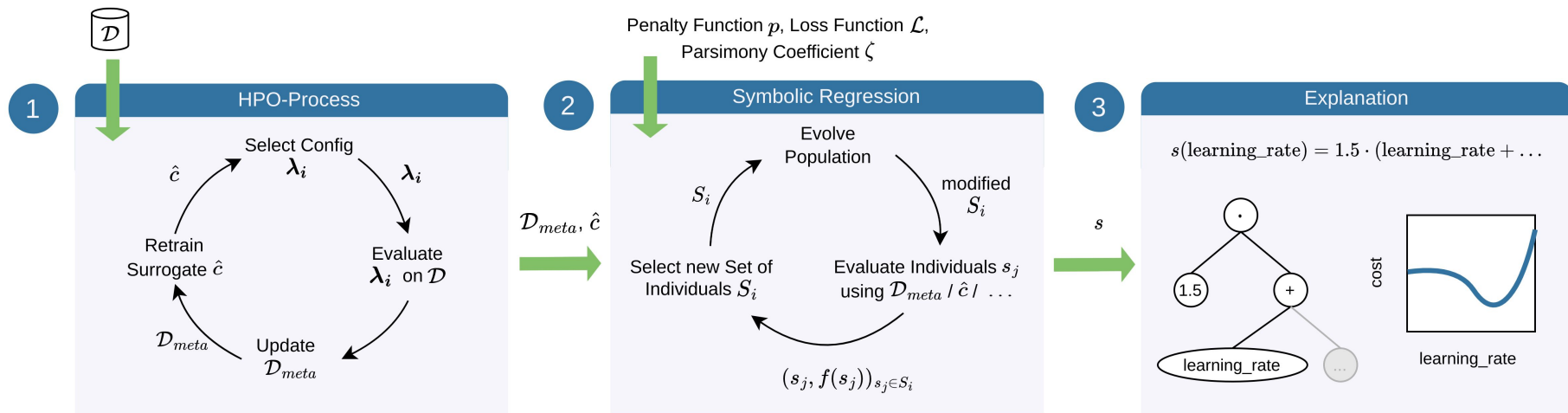


[Segel et al. AutoML'23]



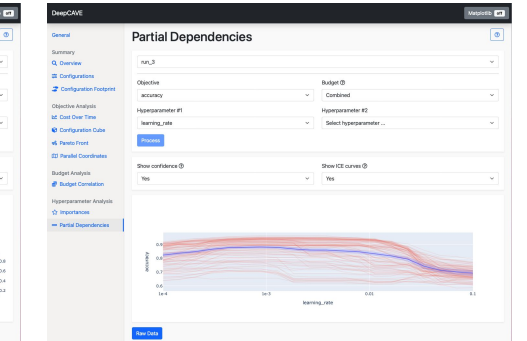
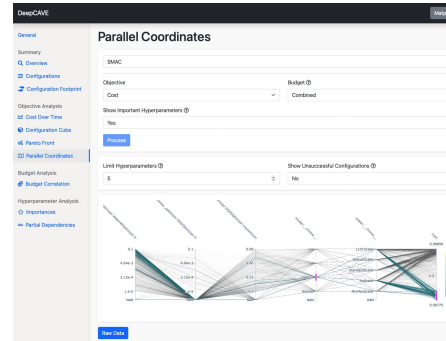
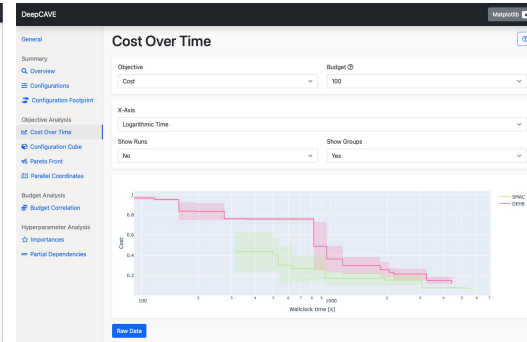
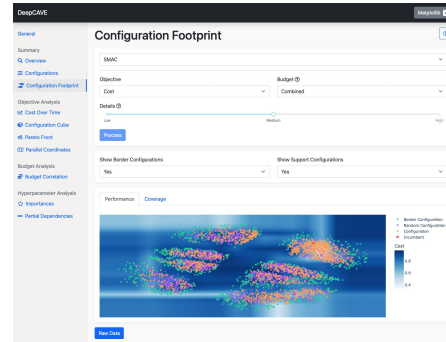
How to get more insights into hyperparameter effects?

- Employ **symbolic regression** to learn an **interpretable formula** that captures the relationship between hyperparameter configurations and model performance



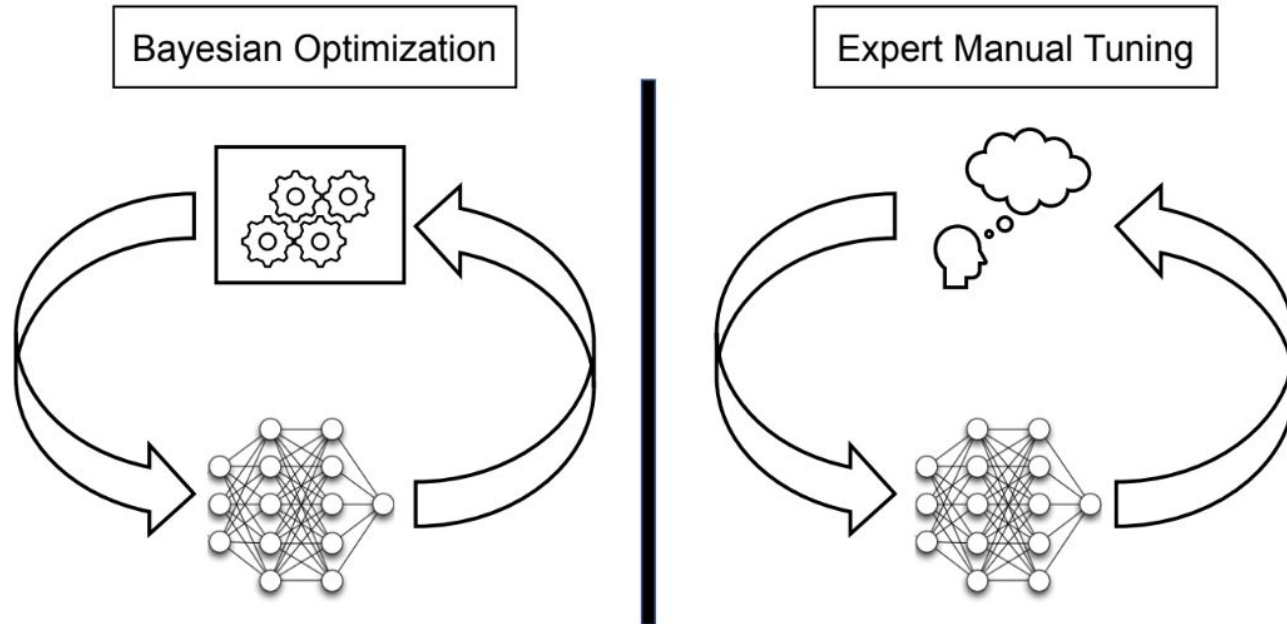
DeepCAVE [\[Sass et al. 2022\]](#)

- **Interactive Dashboard** to self-analyze optimization runs/processes.
- **Analyzing while optimizing**
- **Exploration of multiple areas** like performance, hyperparameter and budget analysis.
- **Modularized plugin** structure with access to selected runs/groups to provide maximal flexibility.
- **Asynchronous execution** of expensive plugins and caching of their results.
- **API mode** gives you full access to the code

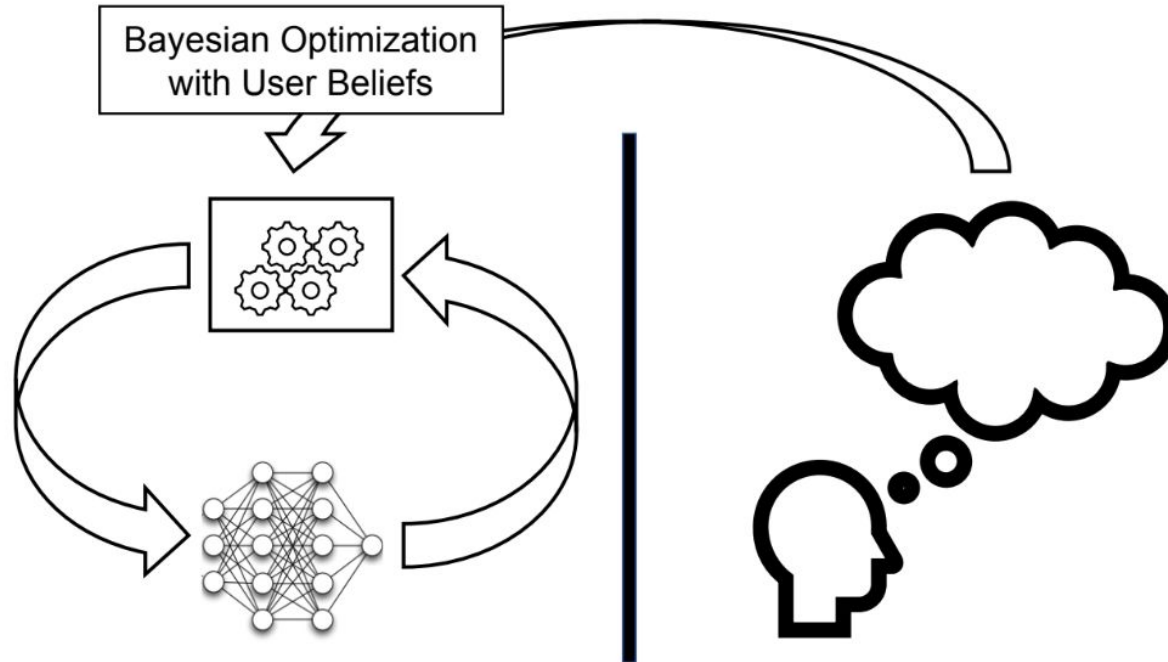


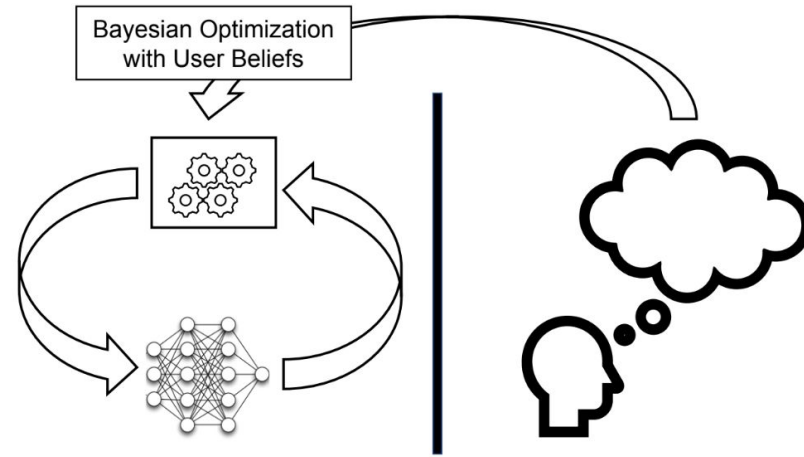
Interaction I: Expert-Priors

Bayesian Optimization vs Manual Tuning for HPO



Bayesian Optimization with Expert Knowledge



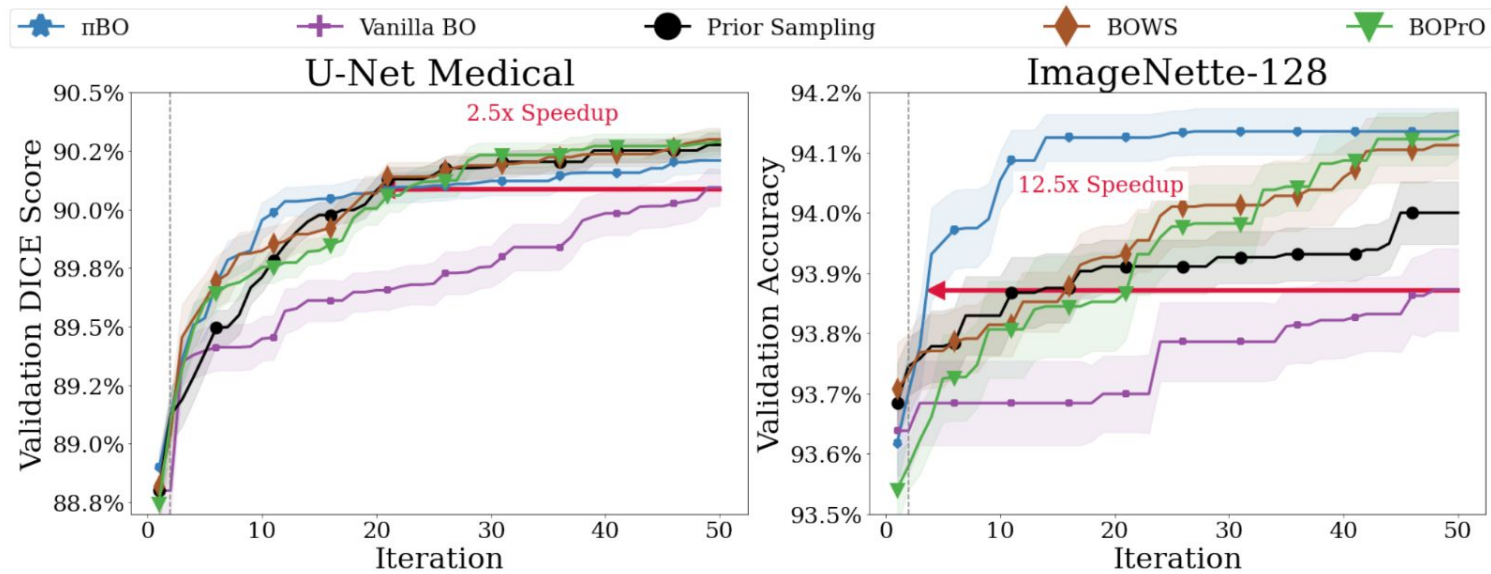


$$\mathbf{x}_n \in \arg \max_{\mathbf{x} \in \mathcal{X}} \alpha(\mathbf{x}, \mathcal{D}_n) \pi(\mathbf{x})^{\beta/n}$$

Acquisition Function

User Prior

Speed of forgetting user prior



- Uses expert knowledge to speed up Bayesian Optimization
- Robust also against wrong beliefs
- Substantially speeds up AutoML
- Follow up with PriorBand [\[Mallik et al. NeurIPS'23\]](#)

Interaction II: Preferences for Multi-Objective AutoML

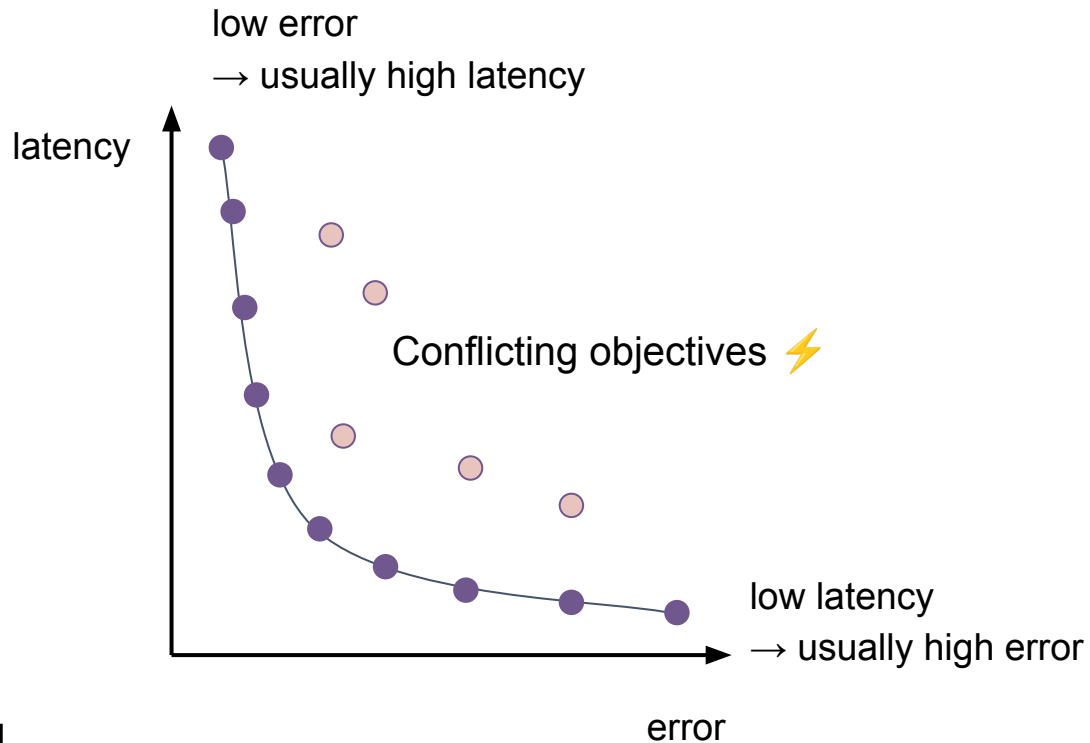
Multi-Objective AutoML

In practice, we often care about more than a single objective, e.g.

- error,
- inference time,
- unfairness,
- energy consumption,
- model complexity,
- and many more

~~Goal: Find a Neural Network with high accuracy and low latency~~

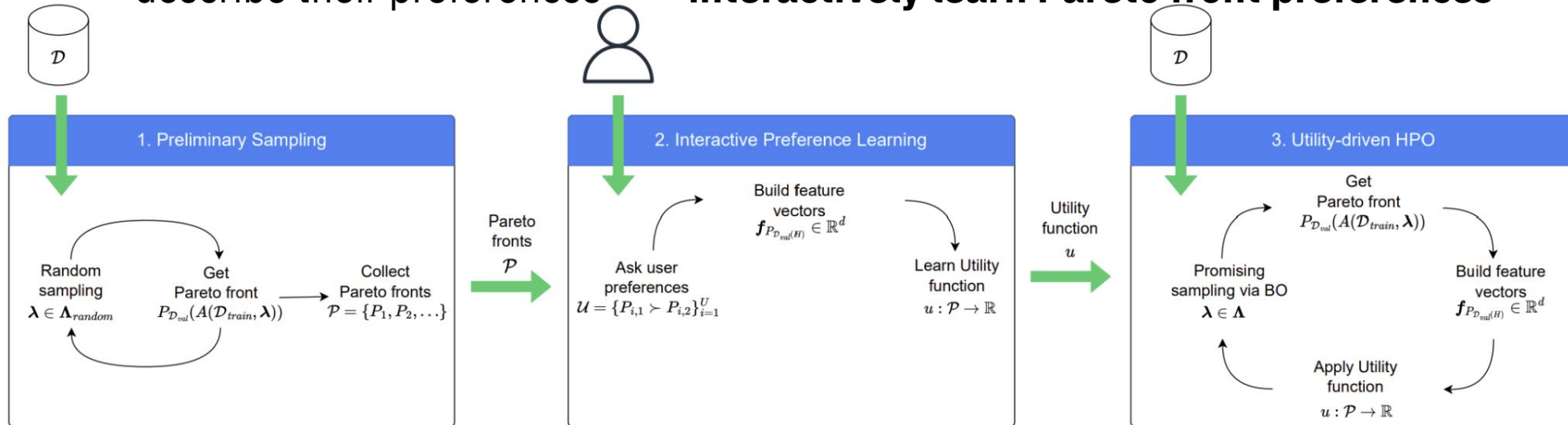
Goal: Find the Pareto Set of Neural Networks that balance accuracy and latency.



Interactive HPO in Multi-Objective Problems via Preference Learning [Giovannelli et al. AAI'24]



- Multi-objective (Auto)ML gets more and more important
 - e.g., hardware-aware NAS, fairness-aware AutoML or energy-efficient AutoML
- Practical challenge:** Different multi-objective indicators lead to different approximated Pareto fronts and users cannot always mathematically describe their preferences \Rightarrow **interactively learn Pareto front preferences**



Evaluation of Preference-Learned Indicators

[[Giovannelli et al. AAI'24](#)]



- Benchmark:
 - LCBench
 - Accuracy vs. Energy-Consumption
- Let's assume : User randomly chose a multi-objective (MO) indicator, but was actually hoping for the behavior of another MO indicator
- \Rightarrow learned preferences are better than randomly choosing a MO indicator

PB\IB	$HV \uparrow$		$SP \downarrow$		$MS \uparrow$		$R2 \downarrow$	
$HV \uparrow$	0.76 (± 0.17)	0.77 (± 0.17)	0.76 (± 0.17)	0.52 (± 0.24)	0.76 (± 0.17)	0.52 (± 0.21)	0.76 (± 0.17)	0.77 (± 0.16)
$SP \downarrow$	0.01 (± 0.01)	0.03 (± 0.02)	0.01 (± 0.01)	0.01 (± 0.0)	0.01 (± 0.01)	0.04 (± 0.03)	0.01 (± 0.01)	0.04 (± 0.02)
$MS \uparrow$	0.61 (± 0.09)	0.19 (± 0.08)	0.61 (± 0.09)	0.19 (± 0.12)	0.61 (± 0.09)	0.65 (± 0.06)	0.61 (± 0.09)	0.23 (± 0.11)
$R2 \downarrow$	0.23 (± 0.16)	0.22 (± 0.16)	0.23 (± 0.16)	0.47 (± 0.23)	0.23 (± 0.16)	0.45 (± 0.21)	0.23 (± 0.16)	0.21 (± 0.16)

AutoML in Constrained Applications

AutoML in Heavily Constrained Applications

[Neutatz et al. VLDBJ'23]



Default AutoML Configuration

Validation Strategy:	Holdout 66/33
Ensembling:	yes
Incremental Training:	yes
Validation split reshuffle:	no

ML Hyperparameter space:	
SVM:	Yes
SVM_tol:	Yes
SVM_C:	Yes
Extra Trees:	Yes
KNN:	Yes
Multilayer Perceptron:	Yes
Any Feature Preprocessor:	Yes
302 hyperparameters	Yes

Dynamic AutoML Configuration

Validation Strategy:	Holdout 46/54
Ensembling:	no
Incremental Training:	yes
Validation split reshuffle:	yes

ML Hyperparameter space:	
SVM:	Yes
SVM_tol:	Yes
SVM_C:	No
Extra Trees:	Yes
KNN:	No
Multilayer Perceptron:	No
Any Feature Preprocessor:	No
302 hyperparameters	Yes/No

ML Pipeline

For SVM, the **model parameters** are the weights w :

$$\left[\frac{1}{n} \sum_{i=1}^n \max(0, 1 - y_i (w^T x_i - b)) \right] + \lambda \|w\|^2.$$

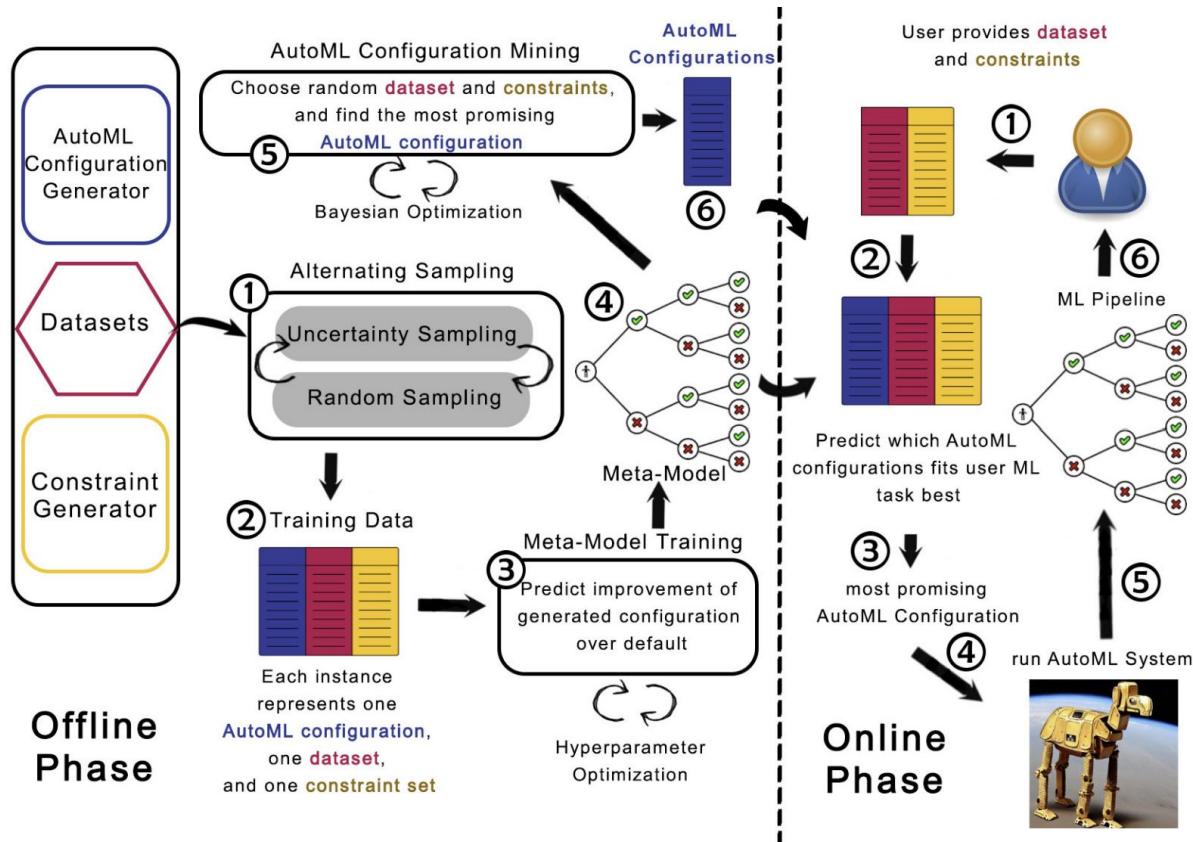
ML Hyperparameters:	
SVM:	Yes
SVM_tol:	1e-5
SVM_C:	1.0 (default)
Extra Trees:	No
KNN:	No
Multilayer Perceptron:	No
Any Feature Preprocessor:	No
302 hyperparameters

Adapt AutoML parameters to
ML task and deactivate undesired
ML hyperparameters

Searches for the optimal ML pipeline in the
defined search space. A pipeline is defined by
the selected ML hyperparameters.

AutoML in Heavily Constrained Applications

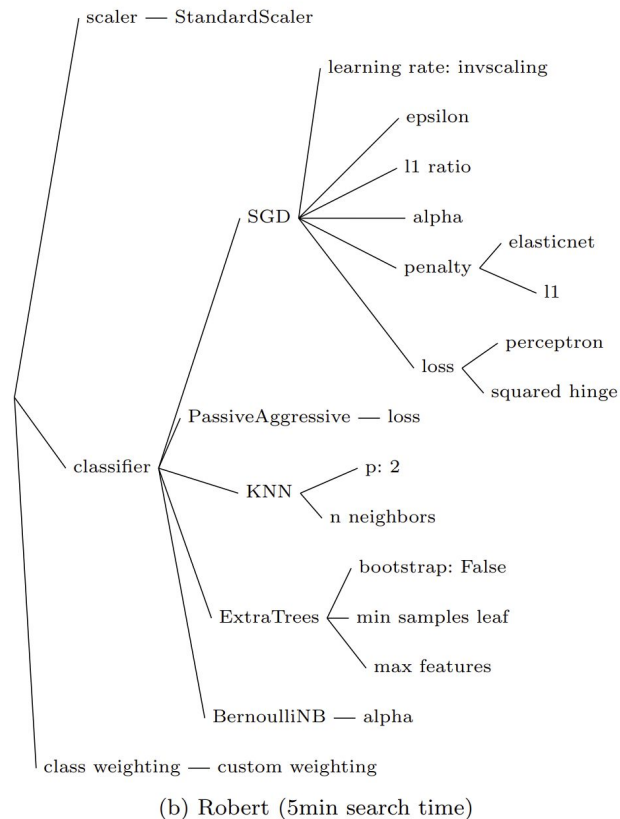
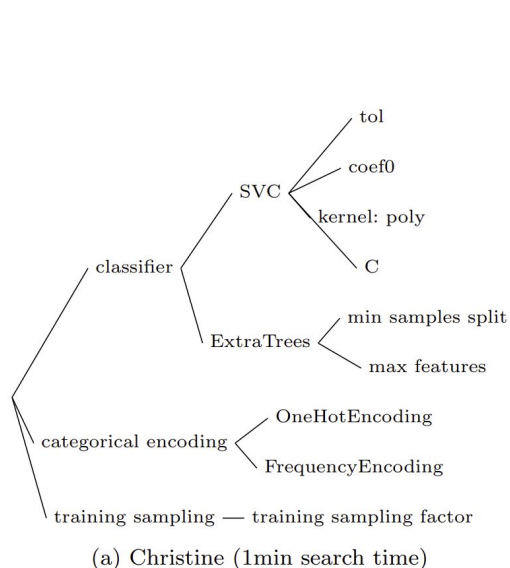
[Neutatz et al. VLDBJ'23]



Possible application constraints:

- AutoML budget
- Inference time
- Memory consumption
- Energy consumption
- Fairness thresholds
- ...

Can it learn to select different configuration spaces? [Neutatz et al. 2023]



Take-Aways for Meta-Learning AutoML Conf.



- **Assumption:** If we invest more time into the development of AutoML packages (incl. meta-learning), we save a lot of compute resources for using it
- **Positive** take-away:
Yes, we can meta-learn how to configure AutoML systems and achieve new state-of-the-art performance
- **Negative** take-away:
We cannot easily do it for large AutoML budgets (beyond 10min) without enormous compute resources
- **Future challenge:** How to configure AutoML on expensive tasks;
“Expensive” can mean:
 - very expensive ML models (e.g., LLMs)
 - very complex configuration spaces with thousands of ML trainings

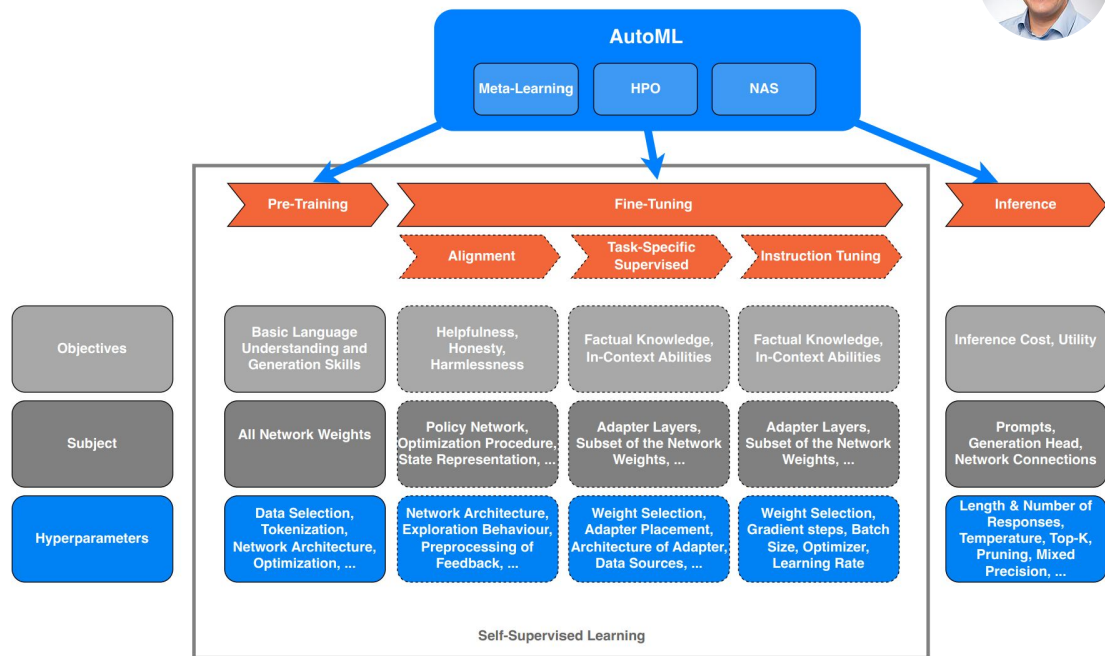
AutoML ↔ LLMs

AutoML → LLMs [\[Tornede et al. 2023\]](#)



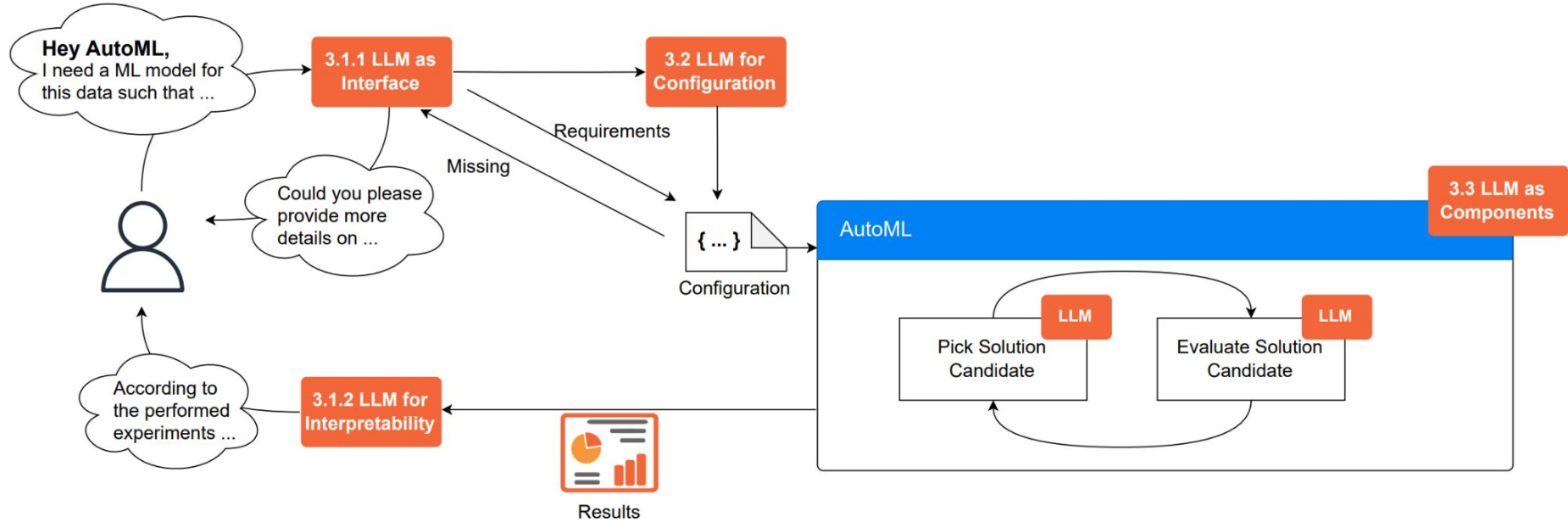
Challenges

1. Cost of Pre-Training Base Models
2. Multitude of Different Stages
3. Multitude of Performance Indicators
4. Combination of Different Learning Paradigms
5. Determining Neural Architectures for LLMs

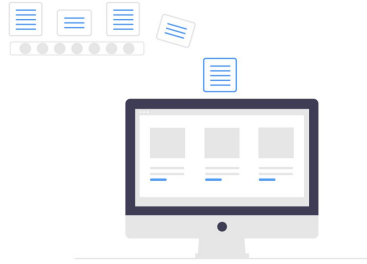




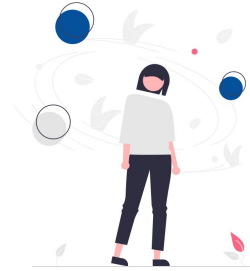
AutoML ← LLMs [Tornede et al. 2023]



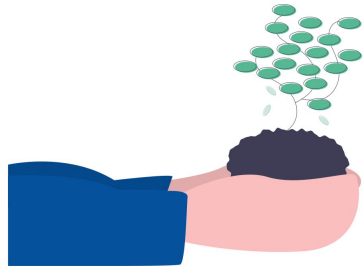
Our Research Foci



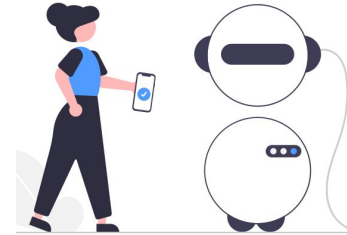
Core AutoML



Human-centered
AutoML



Green AutoML

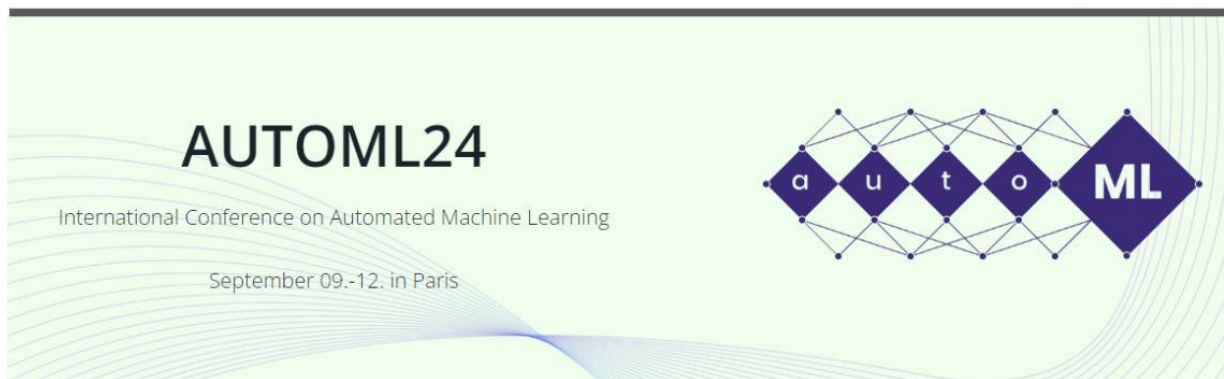


AutoRL

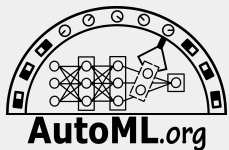





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Place: Hannover, Germany






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